

Contents

Abstract	viii
Acknowledgment	ix
1 Introduction	1
1.1 Indoor Localization	1
1.2 Localization Methods: <i>How it is done?</i>	4
1.2.1 Transmission	6
1.2.2 Characteristics	10
1.2.3 Critique	12
1.3 Thesis Organization: <i>Problems Addressed</i>	13
2 Beacon Placement Problem for Indoor Localization	17
2.1 Beacon Placement Problem (BPP)	17
2.2 Related Works	20
2.2.1 Single Objective Approaches	21
2.2.2 Multi Objective Approaches	22
2.3 Motivation	23
2.3.1 Technological Gaps	23
2.3.2 Proposal	24
3 Parameter Selection	27
3.1 Motivation	27
3.2 Design Elements: <i>Proposed 3D Classification</i>	27
3.3 Analytical Elements of BPP: <i>Control Parameters</i>	29
3.4 Qualitative Assessment of Elements	30
3.4.1 Evaluation Basis: <i>An Optimization Problem</i>	30
3.4.2 Analysis-1: Device Grid Size (DGS) and Beacon Grid Size (BGS)	32
3.4.3 Analysis-2: k and R	33
3.4.4 Analysis-3: Obstacle Grid Size (OGS)	38
3.5 Summary	38

4 Constraint Formulation	39
4.1 Preliminary	39
4.2 Line of Sight Detection	40
4.2.1 Related Works	41
4.2.2 Algorithm	42
4.2.3 PCOC v/s Ray-Voxel Intersection	46
4.2.4 Applicability and Limitations	47
4.3 Assessment of Error Propagation	49
4.4 Optimization Objectives	51
5 An MOO Strategy and Evaluation of Beacon Configurations	53
5.1 Problem Formulation	54
5.1.1 Step-1: Formulating Design Elements	54
5.1.2 Step-2: Formulating Metadata	55
5.1.3 Complete Multi Objective Optimization (MOO) Problem	57
5.2 Proposed Strategy: Optimization Tool Chain (OTC)	57
5.3 Generating Pareto Optimal Beacon Configurations	58
5.3.1 Indoor Designs	58
5.3.2 Simulation Parameters	60
5.3.3 MOO: Obtaining Pareto Solutions	60
5.4 Recommender System: <i>Evaluation and Ranking</i>	68
5.4.1 Performance Evaluation: Network Simulation	68
5.4.2 Ranking	72
5.5 Summary	73
6 Conclusion and Future Work	75
References	i