Contents

Abetr	- act	page
Abstr Ackn	owledgements	ı iii
Conte	ents	v
	f Figures	vii
	f Tables f Symbols	viii xiii
	f Abbreviations	XIII XV
21500		~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~
Chap	oter 1: Introduction	1
1.1	Literature Review	6
	 1.1.1 Control schemes for DC-DC stage of AC-DC-DC Converter 1.1.2 Control schemes for PFC stage of AC-DC-DC Converter 	6 11
	1.1.3 Control schemes for single-stage AC-DC Converter	12
1.2	Event Triggered Control	13
	1.2.1 Concept of Event-triggered Control	14
1.3	Sliding Mode Control	15
1.4	Event-triggered Sliding Mode Control Intergal Sliding mode Control (ISMC)	16 17
1.5 1.6	Motivation and Research Objectives	17
1.7	Organization of Thesis	22
1.8	Publications	23
Char	oter 2: Event-triggered Sliding mode control for Efficiency improvement in DC-DC stage	25
2.1	Isolated Half-bridge converter and SMC Controller Design	25 25
	2.1.1 System Description	26
	2.1.2 Sliding Mode Control	27
2.2	Event-triggered Sliding Mode Control	27
	2.2.1 Existence of practical sliding mode 2.2.2 Stability of the closed loop system in practical Sliding mode	28
	2.2.2 Admissible event-triggering scheme	30 30
2.3	Relationship between ETSMC and HM-SMC	31
	2.3.1 Hysteresis-Modulation based Sliding Mode Control	32
	2.3.2 Comparison of HM-SMC with ETSMC	33
ک ۲	2.3.3 HM-SMC as a special case of ETSMC Simulation Studies	33 34
2.4	2.4.1 Classical SMC vs Event-triggered SMC:	35
	2.4.2 ETSMC and Load Variation	35
2.5	Experimental Studies	35 37
	2.5.1 Classical SMC vs Event-triggered SMC	37
	2.5.2 ETSMC and Input Variation2.5.3 ETSMC and Load Variation	38
	2.5.4 Efficiency improvement	39 40
2.6	Summary	41
Char	stor 2. Event triggered Sliding Mede Centrel for 2 pro regulator DEC stage	42
3.1	oter 3: Event-triggered Sliding Mode Control for a pre-regulator PFC stage Background of Non-linear loads	43 45
3.2	Preliminaries of Loss-free Resistor	45
3.3	Sliding mode based loss-free resistor (SLFR)	46
	3.3.1 Switching function	47
	3.3.2 Control Law	47
	3.3.3 Equivalent Control 3.3.4 Ideal Sliding Dynamics Analysis	48 48
	3.3.5 Analysis of System dynamics	40 49
3.4	Event-triggered SLFR	49
-	3.4.1 Event-triggered SMC for PFC	50
	3.4.2 Comparison of HM-SMC and ETSMC	50 51
3.5	Simulation and Experimentation Studies 3.5.1 Event-triggered vs Classical SLFR	51 51
		, ,

	3.5.2 ETSMC and Load variation	52
	3.5.3 Experimental validation	53 54
3.6	Summary	54
~		
-	eter 4: Event-triggered Sliding Mode Control for Single-stage single-phase PFC application	55
4.1	Adaptive Sliding mode based Loss Free Resistor (ASLFR)	56
4.2	Realizing Adaptive Sliding mode based Loss free Resistor (ASLFR)	57
	4.2.1 General Model	57
	4.2.2 System Description	58
	4.2.3 Proposed Switching function	59
	4.2.4 Reference current generation 4.2.5 Control Law	59 60
	4.2.6 Equivalent Control	60
4.3	Analysis of the Sliding Mode Control	60
ч• <u>)</u>	4.3.1 Reachability Condition	61
	4.3.2 Stability of the closed loop system during Sliding mode	62
4.4	Simulation Studies	64
• •	4.4.1 Adaptive nature of proposed SLFR	64
	4.4.2 Comparative Analysis	66
4.5	Experimental Studies	68
	4.5.1 Test Case-I: Response to Load Transient	69
	4.5.2 Test Case-II: Response to Line Variation	70
	4.5.3 Test Case-III: Response to change in Reference Output Voltage	71
-	4.5.4 Harmonic Analysis	72
4.6	Event-triggered Implementation of ASLFR	73
	4.6.1 Classical v/s ETSMC	73
47	4.6.2 ETSMC and Load Variation	75 76
4.7	Summary	70
Chan	oter 5: Adaptive Sliding mode based Loss-free Resistor for a single stage three-phase	
Спар	modular PFC application	
5.1	System Description	77 78
יינ	5.1.1 System Dynamics	79
	5.1.2 Design for CCM operation	80
5.2	Proposed Control Scheme	81
<u></u>	5.2.1 Switching function	82
	5.2.2 Reference current generation	83
	5.2.3 Control Law	83
	5.2.4 Equivalent Control	84
5.3	Analysis of the Sliding Mode Control	84
	5.3.1 Reachability Condition	84
	5.3.2 Stability of the closed loop system during Sliding mode	85 88
5.4	Simulation Studies	88
	5.4.1 Adaptive nature of proposed SLFR	88
. .	5.4.2 Comparative Analysis Experimental Studies	90 91
5.5	5.5.1 Test Case-I: Steady state Response	
	5.5.2 Test Case-II: Response to Load Transient	92 94
	5.5.3 Test Case-III: Response to Line Variation	9 4 95
	5.5.4 Test Case-IV: Response to change in Reference Output Voltage	95 95
	5.5.5 Harmonic Analysis	96
5.6	Summary	96 96
-		
Chap	oter 6: Integral Sliding mode Control for PFC and ZSC Converters	99
6.1	Principle of ISM based Controller	100
	6.1.1 Switching Surface	101
	6.1.2 Control Law	101
	6.1.3 Existence of Sliding mode	102
6.2	Single stage Boost PFC Application	103
	6.2.1 System Description and dynamic model	103
	6.2.2 Proposed ISM Control (The overall control)	104
	6.2.3 Simulation Studies	107
	6.2.4 Case I: Transient response	107
6 7	6.2.5 Case II: Steady state response ISM Controller for Z-Source Converter with Uncertainty in Parameters	107 110
6.3	6.3.1 System description and dynamic modelling	110
	6.3.2 Proposed ISM Control (The overall control)	113
	6.3.3 Design of PID controller using the Reduced order model	113
	6.3.4 Effects of Asymmetry in the Z-network	116

6.3.5 Simulation Studies 6.4 Summary	117 119
Chapter 7: Discussion and Conclusion	121
References	125