

Contents

	<i>page</i>
Abstract	<i>i</i>
Acknowledgements	<i>iii</i>
Contents	<i>v</i>
List of Figures	<i>vii</i>
List of Tables	<i>viii</i>
List of Symbols	<i>ix</i>
List of Abbreviations	<i>x</i>
Chapter 1: Introduction	1
1.1 Constant Power Loads: Sources, Behaviour and Effects	3
1.2 Small-signal Stability of Basic DC/DC Converters with CPL	4
1.2.1 Buck Converter	5
1.2.2 Boost Converter	5
1.2.3 Buck-Boost Converter	6
1.2.4 Bidirectional Buck-Boost Converter	7
1.3 Stability of a DC Microgrid with CPL	7
1.4 Review of Literature	8
1.4.1 Passive Damping	8
1.4.2 Active Damping	9
1.4.3 Feedback Linearization	13
1.4.4 Pulse Adjustment	14
1.4.5 Sliding Mode Control	14
1.4.6 Synergetic Control	15
1.4.7 Passivity Based Control	16
1.4.8 Power Shaping Stabilization	17
1.4.9 Coupling Based Techniques	17
1.5 Motivation	17
1.6 Research Objectives	19
1.7 Organization of the Thesis	20
1.8 Publications	21
Chapter 2: Mitigation of Destabilizing Effects of CPL in a Boost Converter Feeding Total CPL	23
2.1 Mitigation of CPL effects in Boost Converter using SMC	24
2.1.1 System Modeling of Boost Converter with CPL	24
2.1.2 Design of PWM based SMC	25
2.1.3 Existence of Sliding Mode and Stability of Surface	26
2.1.4 Validation of the Proposed Controller	28
2.2 Mitigation of CPL Effects using SMC designed with Modified Switching Function	34
2.2.1 Modified Switching Function	34
2.2.2 Discontinuous SMC using Modified Switching Function	34
2.2.3 Existence of Sliding Mode with Discontinuous SMC	34
2.2.4 PWM Based SMC using Modified Switching Function	36
2.2.5 Existence of Sliding Mode with PWM Based SMC	36
2.2.6 Stability of Modified Switching Surface	36
2.2.7 Simulation Studies and Discussion	38
2.2.8 Experimental Validation of the Proposed SMCs	42
2.3 Emulation of DC CPL (Electronic Load)	45
2.3.1 CPL Emulation Circuit	47
2.3.2 Power Circuit Modeling	48
2.3.3 Proposed Sliding Mode Controller	48
2.3.4 Existence of Sliding Mode	48
2.3.5 Robustness Analysis	50
2.3.6 Algorithm to Design DC CPL	51
2.3.7 Simulation Studies and Experimental Results	51
2.4 Summary	57
Chapter 3: Mitigation of Destabilizing Effects of CPL in a Buck Converter Feeding a Mixed Load	59
3.1 Mathematical Modeling of Buck Converter with Mixed Load	59

3.2	Sliding Mode Control Design	60
3.2.1	<i>Discontinuous SMC</i>	60
3.2.2	<i>PWM Based SMC</i>	63
3.2.3	<i>Simulation Studies</i>	64
3.2.4	<i>Experimental Validation</i>	70
3.3	Summary	71
Chapter 4: Mitigation of Destabilizing Effects of CPL in a Buck-Boost Converter Feeding a Composite Load		75
4.1	Mitigation of the Destabilizing effects of CPL in Buck-Boost Converter	76
4.1.1	<i>Mathematical Modeling of Converter Supplying Composite Load</i>	76
4.1.2	<i>Sliding Mode Control Design</i>	77
4.1.3	<i>Real-time Simulation Studies</i>	79
4.2	Mitigation of CPL induced instability effects in Bidirectional DC/DC Converter	83
4.2.1	<i>Modeling of Bidirectional DC/DC Converter</i>	86
4.2.2	<i>Sliding mode control design</i>	88
4.2.3	<i>Real-time Simulation Studies</i>	91
4.3	Summary	93
Chapter 5: Mitigation of Destabilizing Effects of CPLs in an Islanded DC Microgrid		95
5.1	Robust Control of Islanded DC Microgrid with Composite Load	96
5.1.1	<i>System Modeling of DCMG with Composite Load</i>	96
5.1.2	<i>Sliding Mode Control Design</i>	99
5.1.3	<i>Existence of Sliding Mode and Stability of Switching Surface</i>	101
5.1.4	<i>Real-time Simulation Studies</i>	104
5.2	Robust Control of Prototype PV based DC Microgrid	108
5.2.1	<i>Test System and its Operating Modes</i>	108
5.2.2	<i>Mathematical Modeling of Island DC Microgrid</i>	111
5.2.3	<i>Sliding Mode Control Design</i>	112
5.2.4	<i>Stability on Switching Surface</i>	114
5.2.5	<i>Simulation Studies and Experimental Results</i>	116
5.3	Summary	122
Chapter 6: Conclusions and Future Work		123
Annexure A: Introduction to Sliding Mode Control		127
A.1	Sliding Mode Control Design	127
A.1.1	<i>Design of a Stable Switching Function</i>	129
A.1.2	<i>Existence of Sliding Mode</i>	130
A.2	Stability of the Switching Surface	130
References		133